

## APPENDIX E

### MULTIVARIATE GAUSSIAN INTEGRALS

Starting from the formula

$$\int_{-\infty}^{\infty} e^{-x^2} dx = \sqrt{\pi} \quad (\text{E-1})$$

it follows that

$$\int \dots \int_{-\infty}^{\infty} dx_1 \dots dx_n \exp \left\{ -\frac{1}{2} \sum_{i=1}^n a_i x_i^2 \right\} = \frac{(2\pi)^{n/2}}{\sqrt{a_1 a_2 \dots a_n}}, \quad a_i > 0. \quad (\text{E-2})$$

Now carry out a real nonsingular linear transformation:

$$x_i = \sum_{j=1}^n B_{ij} q_j, \quad 1 \leq i \leq n, \quad (\text{E-3})$$

where  $\det(B) \neq 0$ . Then, going into matrix notation,

$$\sum a_i x_i^2 = q^T B^T A B q = q^T M q \quad (\text{E-4})$$

where

$$A_{ij} \equiv a_i \delta_{ij} \quad (\text{E-5})$$

is a positive definite diagonal matrix. The volume element transforms according to the Jacobian rule

$$dx_1 \dots dx_n = |\det(B)| dq_1 \dots dq_n \quad (\text{E-6})$$

and

$$\det(M) = \det(B^T A B) = [\det(B)]^2 \det(A). \quad (\text{E-7})$$

The matrix  $M$  is by definition real, symmetric, and positive definite; and by proper choice of  $A$ ,  $B$  any such matrix may be generated in this way. The integral (E-2) may then be written as

$$\int \dots \int \exp \left\{ -\frac{1}{2} q^T M q \right\} |\det(B)| dq_1 \dots dq_n \quad (\text{E-8})$$

and so the general multivariate Gaussian integral is

$$I = \int \dots \int \exp \left[ -\frac{1}{2} q^T M q \right] dq_1 \dots dq_n = \frac{(2\pi)^{n/2}}{\sqrt{\det(M)}}. \quad (\text{E-9})$$

**Partial Gaussian Integrals.** Suppose we don't want to integrate over all the  $\{q_1 \dots q_n\}$ , but only the last  $r = n - m$  of them;

$$I_m \equiv \int \dots \int \exp \left\{ -\frac{1}{2} q^T M q \right\} dq_{m+1} \dots dq_n \quad (\text{E-10})$$

to do this, break  $M$  down into submatrices

$$M = \begin{pmatrix} U_0 & V \\ V^T & W_0 \end{pmatrix} \quad (\text{E-11})$$

and likewise separate the vector  $q$  in the same way:

$$q = \begin{pmatrix} u \\ w \end{pmatrix}. \quad (\text{E-12})$$

by writing  $\{q_1 = u_1, \dots, q_m = u_m\}$  and  $\{q_{m+1} = w_1, \dots, q_n = w_r\}$ . Then

$$Mq = \begin{pmatrix} U_0 & V \\ V^T & W_0 \end{pmatrix} \begin{pmatrix} u \\ w \end{pmatrix} \quad (\text{E-13})$$

and

$$q^T Mq = u^T U_0 u + u^T V w + w^T V^T u + w^T W_0 w \quad (\text{E-14})$$

so that  $I_m$  becomes

$$I_m = \exp\left(-\frac{1}{2} u^T U_0 u\right) \int \dots \int \exp\left\{-\frac{1}{2} [w^T W_0 w + u^T V w + w^T V^T u]\right\} dw_1 \dots dw_r \quad (\text{E-15})$$

To prepare to integrate out  $w$ , first complete the square on  $w$  by writing the exponent as

$$[\dots] = (w - \hat{w})^T W_0 (w - \hat{w}) + C \quad (\text{E-16})$$

and equate terms in (E-14) and (E-16) to find  $\hat{w}$  and  $C$ :

$$w^T W_0 w + u^T V w + w^T V^T u = w^T W_0 w - \hat{w}^T W_0 w - w^T W_0 \hat{w} + \hat{w}^T W_0 \hat{w} + C \quad (\text{E-17})$$

This requires (since it must be an identity in  $w$ ):

$$u^T V = -\hat{w}^T W_0 \quad (\text{E-18})$$

$$V^T u = -W_0 \hat{w} \quad (\text{E-19})$$

$$\hat{w}^T W_0 w + C = 0 \quad (\text{E-20})$$

or,

$$\hat{w} = -W_0^{-1} V^T u \quad (\text{E-21})$$

$$C = -(u^T V W_0^{-1}) W_0 (W_0^{-1} V^T u) = u^T V W_0^{-1} V^T u \quad (\text{E-22})$$

Then  $I_m$  becomes

$$I_m = e^{-\frac{1}{2}(u^T U_0 u + C)} \int \dots \int \exp\left\{-\frac{1}{2} (w - \hat{w})^T W_0 (w - \hat{w})\right\} dw_1 \dots dw_r. \quad (\text{E-23})$$

But by (E-9) this integral is

$$\frac{(2\pi)^{r/2}}{\sqrt{\det(W_0)}} \quad (\text{E-24})$$

and from (E-18)

$$u^T U_0 u + C = u^T [U_0 - V W_0^{-1} V^T] u. \quad (\text{E-25})$$

The general partial Gaussian integral is therefore

$$I_m = \int \dots \int \exp\left[-\frac{1}{2} q^T M q\right] dq_{m+1} \dots dq_n = \frac{(2\pi)^{\frac{n-m}{2}}}{\sqrt{\det(W_0)}} \exp\left\{-\frac{1}{2} u^T U u\right\} \quad (\text{E-26})$$

where

$$U \equiv U_0 - V W_0^{-1} V^T \quad (\text{E-27})$$

is a “renormalized” version of the first  $(m \times m)$  block of the original matrix  $M$ .

This result has a simple intuitive meaning in application to probability theory. The original  $(n \times 1)$  vector  $q$  is composed of an  $(m \times 1)$  vector  $u$  of “interesting” quantities that we wish to estimate, and an  $(r \times 1)$  vector  $w$  of “uninteresting” quantities or “nuisance parameters” that we want to eliminate. Then  $U_0$  represents the inverse covariance matrix in the subspace of the interesting quantities,  $W_0$  is the corresponding matrix in the “uninteresting” subspace, and  $V$  represents an “interaction”, or correlation, between them.

It is clear from (E-27) that if  $V = 0$ , then  $U = U_0$ , and the *pdf*'s for  $u$  and  $w$  are independent. Our estimates of  $u$  are then the same whether or not we integrate  $w$  out of the problem. But if  $V \neq 0$ , then the renormalized matrix  $U$  contains effects of the nuisance parameters. Two components,  $u_1$  and  $u_2$ , that were uncorrelated in the original  $M^{-1}$  may become correlated in  $U^{-1}$  due to their common interactions (correlations) with the nuisance parameters  $w$ .

**Inversion of a Block Form matrix.** The matrix  $U$  has another simple meaning, which we see when we try to invert the full matrix  $M$ . Given an  $(n \times n)$  matrix in block form

$$M = \begin{pmatrix} U_0 & V \\ X & W_0 \end{pmatrix} \quad (\text{E-28})$$

where  $U_0$  is an  $m \times m$  submatrix, and  $W_0$  is  $(r \times r)$  with  $m + r = n$ , try to write  $M^{-1}$  in the same block form:

$$M^{-1} = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \quad (\text{E-29})$$

Writing out the equation  $MM^{-1} = 1$  in full, we have four relations of the form  $U_0 A + V C = 1$ ,  $U_0 B + V D = 0$ , etc. If  $U_0$  and  $W_0$  are nonsingular, there is a unique solution for  $A$ ,  $B$ ,  $C$ ,  $D$  with the result

$$M^{-1} = \begin{pmatrix} U^{-1} & -U_0^{-1} V W_0^{-1} \\ -W_0^{-1} X U^{-1} & W_0^{-1} \end{pmatrix} \quad (\text{E-30})$$

where

$$U \equiv U_0 - V W_0^{-1} X \quad (\text{E-31})$$

$$W \equiv W_0 - X U_0^{-1} V \quad (\text{E-32})$$

are “renormalized” forms of the diagonal blocks. Conversely, (E-30) can be verified by direct substitution into  $MM^{-1} = 1$  or  $M^{-1}M = 1$ . If  $M$  is symmetric as it was above, then  $X = V^T$ .

Another useful and nonobvious relation is found by integrating  $u$  out of (E-26). On the one hand we have from (E-9),

$$\int \dots \int \exp\left\{-\frac{1}{2} u^T U u\right\} du_1 \dots du_m = \frac{(2\pi)^{m/2}}{\sqrt{\det(U)}} \quad ((\text{E-33}))$$

but on the other hand, if we integrate  $\{u_1 \dots u_m\}$  out of (E-26), the final result must be the same as if we had integrated all the  $\{q_1 \dots q_n\}$  out of (E-9) directly: so (E-9), (E-26), (E-33) yield

$$\det(M) = \det(U) \det(W_0) \quad (\text{E-34})$$

Therefore we can eliminate  $W_0$  and write the general partial Gaussian integral as

$$\int \cdots \int \exp\left[-\frac{1}{2} q^T M q\right] dq_{m+1} \cdots dq_n = \left[\frac{(2\pi)^{n/2}}{\det(M)}\right] \left[\frac{\det(U)}{(2\pi)^{m/2}}\right] \exp\left\{-\frac{1}{2} u^T U u\right\} \quad (\text{E-35})$$